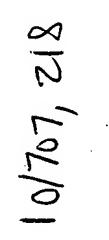
	Туре	# 1	Hits	Search Text	DBs	Time Stamp
H	BRS	L1	384	((scan scanner scanning reader) with ((red with blue with green) color)) same ccd same (linear linearly)	USPAT	2007/04/10 15:00
~	BRS	L2	150	((scan scanner scanning reader) with ((red with blue with green) color)) with ccd with (linear linearly)	USPAT	2007/04/10 14:54
ო	BRS	1.3	148	2 and @ad<"20031127"	USPAT	2007/04/10 14:55
4	BRS	L4	10	((scan scanner scanning reader) with ((red with blue with green) color)) same ccd same (set with (linear linearly) with image)	USPAT	2007/04/10 15:08
LO.	BRS	I.5	8 9	ccd with sensor with array with (divide dividing division divide subdividing subdivision subsubdivided sub-dividing sub-division subdivided partition partitioned partitioning)	USPAT	2007/04/10 15:32
9	BRS	L6	12	ccd with sensor with array with (divide dividing division divide subdivide subdividing subdivision subsubdivided sub-dividing sub-division subdivided partition partitioned partitioning) and ((camera photograph picture) with (scan scanner scanning scanned))	USPAT	2007/04/10 15:41
7	BRS	L7	. <u>.</u> <u></u>	ccd with sensor with array with (divide dividing division divide subdivide subdividing subdivision subsubdivided sub-dividing sub-division subdivided partition partitioned partitioning) and ((cameraphotograph picture) with (scan scanner scanning scanned))	US-PGPUB; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 15:39
	BRS	. 8 	ري ا	ccd with sensor with matrix with (divide dividing division divide subdivide subdividing subdivision subsubdivided sub-divided sub-dividing sub-division subdivided partition partitioned partitioning) and ((cameraphotograph picture) with (scan scanner scanning scanned))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:19
6	BRS	L10	21	(scanner mouse camera) same ccd same ((sensor near3 (array matrix)) with (divide dividing division divide Usubdivide subdividing subdivision subdivided sub-divide Sub-dividing sub-division sub-divided partition partitioning))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:25



	Туре	# 1	Hits	Search Text	DBs	Time Stamp
10	BRS	L9	6	(scanner mouse camera) with ccd with (sensor near3 (array matrix)) with (divide dividing division divide subdivide subdividing subdivision subdivided sub-divided partition partitioning)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10
11	BRS	177	0	(scanner with mouse with camera) same ccd same ((sensor near3 (array matrix)) with (divide dividing division divide subdivided subdivided subdivided subdivided subdivided sub-divided sub-divided partition partition))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:26
12	BRS	L12	0	(scanner with mouse with camera) same ccd same ((sensor near3 (array matrix)) with (split splitted splitting))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:26
13	BRS.	L13		(scanner with mouse with camera) and ccd and ((sensor near3 (array matrix)) with (divide dividing division divide subdivided subdivided subdivided sub-dividing sub-division sub-divided partition partition))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:28
14	BRS	L14	4	(scanner and mouse and camera) and ccd and (sensor near3 (array matrix)) with (divide dividing division divide subdivides subdividing subdivision subdivided subdivided subdivided sub-dividing sub-division sub-divided partition partition))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:35
ب د	BRS	L15	4 0	(scanner and camera) and ccd and ((sensor near3 (array matrix)) with (divide dividing division divide subdivide subdividing subdividing subdivision subdivided sub-divide subdividing sub-division sub-divided partition partitioned partitioning))	ray ivideUS-PGPUB; USPAT; USOCR; EPO; JPO; oned DERWENT; IBM_TDB	2007/04/10 17:30
16	BRS	L16 .	. 36	15 not 14	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 16:35
17	BRS	L17	12	(scanner and camera) and ccd and ((sensor near3 (array matrix)) with (split splitting))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10
18	BRS	L18	33	(mouse and camera) and ccd and ((sensor near3 (array matrix)) with (divide dividing division divide subdivide subdividing subdivision subdivided sub-divide subdividing sub-division sub-divided partition partitioned partitioning split splitting))	y ivideUS-PGPUB; USPAT; USOCR; EPO; JPO; oned DERWENT; IBM_TDB	2007/04/10

Gearch Text			-				
RRS L19 Compuse with camera) and ccd and ((sensor near3 (array) matrix)) with (divide dividing duly) and dividing sub-division sub-division caldivide sub-divise sub-divises of dividing sub-division sub-division partition partitioned DERWERY; LBM_TDB partitioning split splitting) US-POPUB; USPAT; USCCR; EPO; UPO; DERWERY; LBM_TDB partitioning split splitting) US-POPUB; USPAT; USCCR; EPO; UPO; DERWERY; LBM_TDB DERWERY;		Туре		Hits	Search Text	DBs	Time Stamp
BRS L20 31 18 not 19 USCP EPGPUB; USPAT; BAN TOB DEMBENT; IBM TOB DEMBENT; IBM TOB EAST EPG, JPG; EPGPUB; USPAT; EPGPUB; E	19	BRS	L19	. 2	se with camera) and ccd and ((sensor near3 ix)) with (divide dividing division divide ividing sub-divide divided sub-divide ding sub-division sub-divided partition paitioning split splitting))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10-
BRS L21 (mouse) same ((sensor near3 (array matrix)) with ((one first primary) near3 color near3 only)) BRS L22 (mouse) and ((sensor near3 (array matrix)) with ((one first primary) near3 color near3 only)) BRS L23 (sensor near3 (array matrix)) with ((one first primary) US-PGPUB; USPAT; DERWENT; IBM_TDB ((sensor near3 only)) BRS L24 4870 ((sensor near3 (array matrix)) with ((linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with ((linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with (linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with (linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with (linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with (linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with (linear linearly)) DERWENT; IBM_TDB ((sensor near3 (array matrix)) with (linear linearly)) US-PGPUB; USPAT; BRZ L25 23 and 25 23 and 26 23 and 26 24 and (mouse mice) DERWENT; IBM_TDB (US-PGPUB; USPAT; US-PGPUB; USPAT; USPAT; USPAT; USPAT; US-PGPUB; USPAT; USPA	20	BRS	L20	31	not	USPAT; O; JPO; IBM_TDB	2007/04/10 17:31
BRS L22 5 first primary) near3 (array matrix)) with ((one first primary) near3 color near3 only)) BRS L24 4870 ((sensor near3 (array matrix)) with (linear linearly) DERWENT; IBM_TDB BRS L25 82 subdividing subdivision divide subdivide sub-divide sub-div	21	BRS	L21		e) same ((sensor near3 (array matrix)) with (primary) near3 color near3 only))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 17:47
BRS L24 4870 ((sensor near3 (array matrix)) with ((one first primary) US-DGDUB; USPAT; BRS L24 4870 ((sensor near3 (array matrix)) with (linear linearly) USOCR; EPO; JPO; BRS L25 82 subdividing division divide subdivide subdivided partition partition partition between the DERWENT; IBM_TDB USOCR; EPO; JPO; DERWENT	22	BRS	L22	Ŋ	e) and ((sensor near3 (array matrix)) with primary) near3 color near3 only))	UB; EP T;	2007/04/10 17:49
BRS L25 # 4870 ((sensor near3 (array matrix)) with (linear linearly)	23	BRS	L23	56.	sor near3 (array matrix)) with ((one first pr color near3 only))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	2007/04/10 17:50
BRS L25 82 subdividing sub-divided sub-divide sub-divide sub-divided partition partitioned partitioning split splitting)) BRS L25 82 subdividing sub-division sub-divided sub-divide sub-divided partition partitioned partitioning split splitting)) BRS L26 1 23 and 25 23 not 26 23 not 26 25 23 not 26 27 and (mouse mice)) BRS L28 4 27 and (mouse mice) 25 perwent; IBM_TDB US-PGPUB; USPAT;	24	BRS	L24	4870	near3 (array matrix)) with (linear linear	US O; IBN	2007/04/10 17:50
BRS L26 1 23 and 25 USOCR; EPO; JPO; DERWENT; IBM_TDB BRS L27 55 23 not 26 USOCR; EPO; JPO; DERWENT; IBM_TDB BRS L28 4 27 and (mouse mice) USOCR; EPO; JPO; DERWENT; IBM_TDB BRS L28 4 27 and (mouse mice) USOCR; EPO; JPO; DERWENT; IBM_TDB	2 5 5	BRS	L25	8 2	sor near3 (array matrix)) with (linear linear (divide dividing division divide subdivide subdivide sub-divide sub-divide subling sub-division sub-divided partition partititioning split splitting))	; US 20; IBN	2007/04/10 18:00
BRS L27 55 23 not 26 US-PGPUB; USPAT;	5 6	BRS	L26	.	and		2007/04/10 17:51
US-PGPUB; USPAT; BRS L28 4 27 and (mouse mice) DERWENT; IBM_TDB	27	BRS	L27	55	not	' `	2007/04/10 17:58
	58	BRS	L28	4	and (mouse	US O; IBN	2007/04/10 17:59

Stamp	1/10	
Time S	2007/04/10	
DBs	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	
Search Text	((sensor near3 (array matrix)) with (linear linearly) with (divide dividing division divide subdivide subdivide sub-dividing subdivision subdivided partition partitioned partitioning splitting)) and (scanner scan scanned scanning)	
Hits	50	
# Т	L29	
Туре	BRS	
	29	

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	Туре	# -	Hits	Search Text	DBs	Time Stamp
7	BRS	L2	0	((optical near3 sensor near3 array) with (camera photograph picture) with ((red with blue with green) color)) same ccd	USPAT	2007/04/10
7	BRS	L3	32	((sensor near3 array) with (camera photograph picture) with ((red with blue with green) color)) same ccd	USPAT	2007/04/10 11:03
3	BRS	L4	3.0	3 and @ad<"20031127"	USPAŢ	2007/04/10 11:04
4	BRS	1.5	43	((sensor near3 array) with (scan scanner scanning reader) with ((red with blue with green) color)) same ccd	USPAT	2007/04/10
2	BRS	T6	2	4 and 5	USPAT	2007/04/10 11:04
9	BRS	L7	41	(5 not 6) and @ad<"20031127"	USPAT	2007/04/10
7	BRS	L8	10	7 and (block with sensor)	USPAT	2007/04/10 11:08
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	•	•				
				4/10/07, EAST Version: 2.0.3.0		